

Anaphora and Ambiguity in Narratives

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SDRT

- SDRT is a formal, integrated theory of coherence relations.
 - > What coherence relations **mean**.
 - > How coherence structures (graphs) are **constructed**.
- Two main component logics:
- Logic of Information Content for the truth-conditional semantics of graphs.
 - > Logical form, meaning.
- Glue Logic to **construct** these logical forms.
 - > Underspecification, construction.

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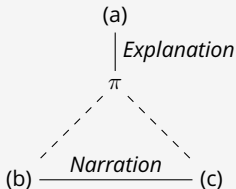
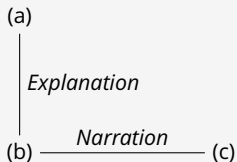


\rightsquigarrow := the *construction algorithm*,

\mapsto := a truth-conditional model-theoretic *embedding*.

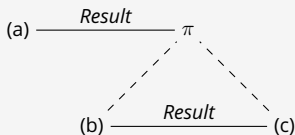
Complex Discourse Units

- (1) a. Arash doesn't trust Akna.
b. She promised to help him once,
c. and then later forgot about it.

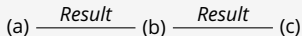


Subtleties

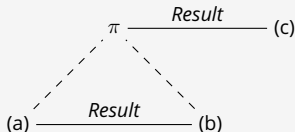
- (2) a. John overslept.
b. So he missed his flight.
c. So he got angry at himself.



- (3) a. John overslept.
b. So he missed his flight.
c. So he took a train.



- (4) a. John overslept.
b. So he missed his flight.
c. So he bought an alarm clock.



Notational Variation

- (5) a. John overslept.
b. So he missed his flight.
c. So he got angry at himself.
- }Result }Result }Result

- (6) a. John overslept.
b. So he missed his flight
c. So he took a train.
- }Result }Result }Result

- (7) a. John overslept.
b. So he missed his flight.
c. So he bought an alarm clock.
- }Result }Result }Result

The Right Frontier

One of the most exciting facts in all of linguistics

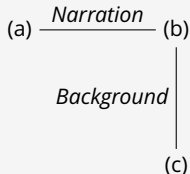
Anaphora follow coherence structure

The anaphora-accessible referents are on the right-most nodes of the graphed discourse structure.

Improving on DRT

- DRT does not (always) make the right predictions for anaphora.

- (8) a. John dropped off his car for repairs.
b. Then he got a rental.
c. It had a broken fuel pump.



- DRT: flat structure.
 - > *his car* available for *it*.
- coherence relations: complex structure.
 - > Narration(a,b) blocks this binding.

Semantics for Discourse

Truth-conditions of *discourses*

- We assign **truth conditional meaning postulates** to the coherence relations themselves.
 - > These postulates tell us something about the **constituent units** of a relation.
- (this is in fact perfectly analogous to “modes of composition” in Fregean-Montogovian semantics)

- The Big Picture:
- Discourse logical forms are built from two languages:
 - > Microstructure (clause level, EDUs)
 - > Macrostructure (discourse level, CDUs)

Microstructure Vocabulary

Variables ($x, y, \dots, e_1, e_2, \dots$); Name symbols (John, Max, ...); Predicate symbols (eat, overlap, actor, ...); connectives ($=, \Rightarrow, \neg, \Diamond$).

Microstructure Formulas (DRSs)

A DRS is a tuple $\langle U, Cond \rangle$ where U is a set of variables, and $Cond$ is a set of conditions.

- For a name N and a variable x , $N(x)$ is a condition.
- For a predicate P and variables x_1, \dots, x_n , $P(x_1, \dots, x_n)$ is a condition.
- For variables x and y , $x = y$ is a condition.
- If C_1 and C_2 are DRSs, $C_1 \Rightarrow C_2$, $\neg C_1$ and $\Diamond C_1$ are conditions.

(add more as needed!)

- I'll use a lot of event variables for neo-Davidsonian semantics.

- Plan: Macrostructure formulas contain **labels** for other formulas and state **how the labelled contents form a discourse**.

Macrostructure Vocabulary

DRSs; coherence relation symbols (Elaboration, Narration, ...); label variables (π, λ, \dots); logical connectives ($\neg, \Rightarrow, \wedge, \Diamond$).

Macrostructure Formulas

- Any DRS K is a macrostructure formula.
(DRSs are like the atoms of the macrostructure)
- For a coherence relation R and label variables α, β , $R(\alpha, \beta)$ is a macrostructure formula.
- If P and Q are macrostructure formulae, then so are $P \wedge Q$, $\neg P$, $\Diamond P$, $P \Rightarrow Q$.

Segmented Discourse Representation Structure

An SDRS is a triple (Π, \mathcal{F}, L) where Π is a set of label variables, $L \in \Pi$ and \mathcal{F} is a function from Π to the macrostructure formulae such that for any $\pi \in \Pi$, either:

- $\mathcal{F}(\pi) = K$ for some DRS K (microstructure).
 - $\mathcal{F}(\pi)$ is a conjunction of formulas of the form $R(\alpha, \beta)$ (where $\alpha, \beta \in \Pi$).
-
- Typically $\pi : K$ abbreviates $\mathcal{F}(\pi) = K$.
 - Typically π_0 denotes the CDU constituting the full discourse.
 - L is the right-most or *last* label: the label for the discourse-final clause (in the linear surface order).

(9) a. John overslept.

b. So he missed his flight.

c. So he took a train.

$$\pi_a \xrightarrow{\text{Result}} \pi_b \xrightarrow{\text{Result}} \pi_c$$

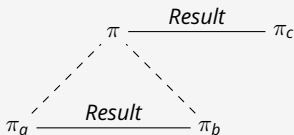
$$\mathcal{F}(\pi_a) = \llbracket (a) \rrbracket$$

$$\mathcal{F}(\pi_b) = \llbracket (b) \rrbracket$$

$$\mathcal{F}(\pi_c) = \llbracket (c) \rrbracket$$

$$\mathcal{F}(\pi_0) = \text{Result}(\pi_a, \pi_b) \wedge \text{Result}(\pi_b, \pi_c)$$

- (10) a. John overslept.
 b. So he missed his flight.
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$$\mathcal{F}(\pi_a) = \llbracket (a) \rrbracket$$

$$\mathcal{F}(\pi_b) = \llbracket (b) \rrbracket$$

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$$\mathcal{F}(\pi_0) = \text{Result}(\pi, \pi_c)$$

$$\mathcal{F}(\pi) = \text{Result}(\pi_a, \pi_b)$$

What about the Right Frontier?

- Some more definitions:

Outscoping

- Note that \mathcal{F} induces an order on Π .
- Say that $\alpha < \beta$ iff α occurs in $\mathcal{F}(\beta)$.
- Let \prec denote the reflexive transitive closure of $<$.
- Call this relation “outscoping”.

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Interpretable SDRS

- A SDRS (Π, \mathcal{F}, L) is **well formed** if:
- There is a unique outscoping-maximal label in Π (“root”).
- \prec is anti-symmetric (in particular, then, it has no circles)

The Right Frontier (formally)

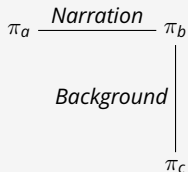
- Let (Π, \mathcal{F}, L) be a well-formed SDRS.

SDRT-Accessibility

Accessibility is defined recursively:

- L is accessible.
- If α is accessible and $\alpha \prec \beta$, then β is accessible.
- If (i) α is accessible, and
(ii) $R(\beta, \alpha)$ occurs in some $\mathcal{F}(\gamma)$, and
(iii) R is subordinating
then β is accessible.

- (11) a. John dropped off his car for repairs.
 b. Then he got a rental.
 c. It had a broken fuel pump.



$$L = \pi_c$$

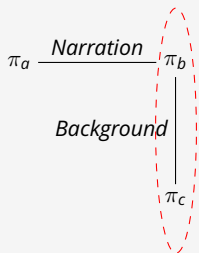
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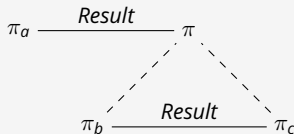
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- (12) a. John overslept.
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$$L = \pi_c$$

$$\mathcal{F}(\pi_a) = \llbracket (a) \rrbracket$$

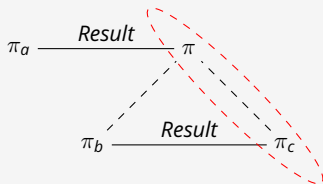
$$\mathcal{F}(\pi_b) = \llbracket (b) \rrbracket$$

$$\mathcal{F}(\pi_c) = \llbracket (c) \rrbracket$$

$$\mathcal{F}(\pi_0) = \text{Result}(\pi_b, \pi_c)$$

$$\mathcal{F}(\pi) = \text{Result}(\pi_a, \pi)$$

- (12) a. John overslept.
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$$L = \pi_c$$

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Summary

- Elementary Discourse Units are Discourse Representation Structures.
- Segmented Discourse Representation Structures are discourse structures on top of these EDUs
- EDUs (microstructure) are constructed by the DRS construction algorithm.
- Within EDUs, anaphora are guided by DRT-accessibility.
- *Across* EDUs, anaphora are guided by the right frontier.

Macrostructure Evaluation

- We already know how to evaluate DRSs.
- We recursively translate a macrostructure formula P into a *microstructure* K such that update with K represents the information in P (not as hard as it sounds!).

The Plan

Linguistic Forms

are interpreted to

SDRSs

describe **discourse** structure

are converted to

DRSs

describe **event** structure

are evaluated in

Models

- A bit of notation:
- For two DRSs $K_1 = \langle U_1, C_1 \rangle$, $K_2 = \langle U_2, C_2 \rangle$, define $K_1 + K_2 = \langle U_1 \cup U_2, C_1 \cup C_2 \rangle$.

Macrostructure-to-Microstructure

Given an SDRS $S = (\Pi, \mathcal{F}, L)$, translate a macro formula P to a DRS $\llbracket P \rrbracket^S$ (say, P interpreted in the discourse structure S).

1. If $P = K$ for a DRS K , then $\llbracket P \rrbracket^S = K$.
- 2a. If $P = Q_1 \wedge Q_2$, then $\llbracket P \rrbracket^S = \llbracket Q_1 \rrbracket^S + \llbracket Q_2 \rrbracket^S$.
- 2b. If $P = \neg Q$, then $\llbracket P \rrbracket^S = \overline{\llbracket Q \rrbracket^S}$
- 2c. If $P = \diamond Q$, then $\llbracket P \rrbracket^S = \overline{\diamond \llbracket Q \rrbracket^S}$
- 2d. If $P = Q_1 > Q_2$, then $\llbracket P \rrbracket^S = \overline{\llbracket Q_1 \rrbracket^S \Rightarrow \llbracket Q_2 \rrbracket^S}$.
3. If $P = R(\alpha, \beta)$ for a coherence relation R , then $\llbracket P \rrbracket^S = \llbracket \text{Info}_R(\mathcal{F}(\alpha), \mathcal{F}(\beta)) \rrbracket^S$
where Info_R is the specific semantic contribution provided by the relation R (a meaning postulate).

Veridicality

- Most coherence relations are **veridical**: they compose to content that entails their parts.

- If R is veridical,

$$\llbracket \text{Info}_R(\alpha, \beta) \rrbracket^S = \llbracket \mathcal{F}(\alpha) \wedge \mathcal{F}(\beta) \wedge \text{Info}'_R(\mathcal{F}(\alpha), \mathcal{F}(\beta)) \rrbracket^S$$

where Info'_R is the specific semantic contribution provided by the relation R (a meaning postulate).

- Not all are veridical.

One more preliminary...

- Note that “microstructure” is just about **clauses**.
- Recall that we associated **events** with verb phrases.
- Let’s call the event associated with the main verb phrase of a clause its **semantic index**.
- Let’s refer to the semantic index of a microstructure K e_K .
- Or, if K is labelled by π , also e_π .

- Elaboration is veridical and adds that the second content *typically* entails the first, but not vice versa, and that the events overlap:
 - > “typically entails” → tomorrow, Friday.

$$\begin{aligned} \text{Info}'_{\text{Elab}}(\mathcal{F}(\alpha), \mathcal{F}(\beta)) = & \quad \mathcal{F}(\beta) > \mathcal{F}(\alpha) \\ & \wedge \neg(\mathcal{F}(\alpha) > \mathcal{F}(\beta)) \\ & \wedge \boxed{\overline{\text{part-of}(e_\beta, e_\alpha)}} \end{aligned}$$

(13) a. John had a great meal.

b. He had salmon.

c. And he had cheese.

- o Do salmon and cheese individually suffice for a great meal, or are they only jointly a great meal

- Wait, Julian, what about CDUs that are parts of further coherence relations?

- Wait, Julian, what about CDUs that are parts of further coherence relations?
- I'm glad you ask: we also need to assign non-microstructure events a semantic index. So, technically:

$$\text{Info}'_{\text{Elab}}(\mathcal{F}(\alpha), \mathcal{F}(\beta)) = \mathcal{F}(\beta) > \mathcal{F}(\alpha) \\ \wedge \neg(\mathcal{F}(\alpha) > \mathcal{F}(\beta)) \\ \wedge \boxed{\begin{array}{c} e \\ \hline \text{part-of}(e_\beta, e_\alpha) \\ e = e_\alpha \end{array}}$$

While we are being technical...

- Actually, if we are being *super* precise, we need to keep track of which label in the SDRS we are evaluating gave rise to this $Info_{\text{Elab}}$ so that we can assign e to that label.
 - So we *should* write this: (keeping track of which label the relation belongs to)
3. $f \llbracket \pi : R(\alpha, \beta) \rrbracket_{M,w}^S g$ iff $f \llbracket Info_R(\pi, \mathcal{F}(\alpha), \mathcal{F}(\beta)) \rrbracket_{M,w}^S g$.

$$Info'_{\text{Elab}}(\pi, \mathcal{F}(\alpha), \mathcal{F}(\beta)) = \mathcal{F}(\beta) > \mathcal{F}(\alpha) \\ \wedge \neg(\mathcal{F}(\alpha) > \mathcal{F}(\beta)) \\ \wedge \boxed{\begin{array}{c} e_\pi \\ \hline \text{part-of}(e_\beta, e_\alpha) \\ e_\pi = e_\alpha \end{array}}$$

- This is the **topic constraint** for events e_α, e_β :

e_π
$\text{part-of}(e_\alpha, e_\pi)$
$\text{part-of}(e_\beta, e_\pi)$
$(K_\alpha \sqcap K_\beta)^{e_\pi}$

- $(K_\alpha \sqcap K_\beta)^{e_\pi}$ is the DRS with index e_π that records ‘the common content’ of K_α and K_β .
 - > Asher & Lascarides 2003: “very difficult to define in practice”.

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- An approximation:
- For a DRS K , let K^e be like K where the semantic index of K has been uniformly replaced by e . Define $(K_\alpha \sqcap K_\beta)^{e_\pi} = K_\alpha^{e_\pi} \sqcap K_\beta^{e_\pi}$

Continuation

- Continuation is the simplest topic relation.

$$\text{Info}'_{\text{Continuation}}(\pi, \mathcal{F}(\alpha), \mathcal{F}(\beta)) = \begin{array}{|l} e_\pi \\ \hline \text{part-of}(e_\alpha, e_\pi) \\ \text{part-of}(e_\beta, e_\pi) \\ (K_\alpha \sqcap K_\beta)^{e_\pi} \end{array}$$

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- (14) a. Essun told the children to search for the cat.
b. Binof searched the garden. } Continuation
c. Tonkee looked in the kitchen. } Result

Continuation

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- (14) a. Essun told the children to search for the cat.
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c. Tonkee looked in the kitchen. } Result
searching for the cat

A closer look

- (15) a. Essun told the children to search for the cat.
b. Binof searched the garden.
c. Tonkee looked in the kitchen. } Continuation
} Result
- searching for the cat*

$$K_b =$$

e_b, b, x, g
Binof(b)
searching(e_b)
actor(e_b, b)
object(e_b, x)
location(e_b, g)
garden(g)

$$K_c =$$

e_c, t, x, k
Tonkee(t)
searching(e_c)
actor(e_c, t)
object(e_b, x)
location(e_c, k)
kitchen(k)

A closer look

- (15) a. Essun told the children to search for the cat.
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c. Tonkee looked in the kitchen. } Continuation
} Result
- searching for the cat*

$$K_b = \begin{array}{|l} \hline e_b, b, x, g \\ \hline \text{Binof}(b) \\ \text{searching}(e_b) \\ \text{actor}(e_b, b) \\ \text{object}(e_b, x) \\ \text{location}(e_b, g) \\ \text{garden}(g) \\ \hline \end{array} \quad K_c = \begin{array}{|l} \hline e_c, t, x, k \\ \hline \text{Tonkee}(t) \\ \text{searching}(e_c) \\ \text{actor}(e_c, t) \\ \text{object}(e_b, x) \\ \text{location}(e_c, k) \\ \text{kitchen}(k) \\ \hline \end{array} \quad (K_b \sqcap K_c)^e = \begin{array}{|l} \hline e, x \\ \hline \text{searching}(e) \\ \text{object}(e, x) \\ \hline \end{array}$$

(I've already resolved the anaphor for the search-event object to the same x in K_b and K_c .)

Info for Narration

- Narration is veridical and adds the information that events are temporally close and reported in order:
 - > “close” is sensitive to context (like “tall”).
- Let $e_1 \approx e_2$ mean that e_1 and e_2 are temporally close.

$$Info'_{\text{Narration}}(\pi, \mathcal{F}(\alpha), \mathcal{F}(\beta)) =$$

 e_π $\text{part-of}(e_\alpha, e_\pi)$ $\text{part-of}(e_\beta, e_\pi)$ $(K_\alpha \sqcap K_\beta)^{e_\pi}$ $\text{post}(e_\alpha) \approx \text{pre}(e_\beta)$

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- (16) a. The terrorist went to the bridge.
b. Then he planted a bomb. } Narration

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- (16) a. The terrorist went to the bridge.
b. Then he planted a bomb. } Narration
on or near the bridge

Another closer look

- (17) a. Binof went to the garden.
b. And looked for the cat. } Narration
looking in the garden

$$K_b = \frac{e_a, b, x, g}{\text{Binof}(b) \text{ going}(e_a) \text{ actor}(e_a, b) \text{ object}(e_b, g) \text{ garden}(g)}$$
$$K_c = \frac{e_b, c}{\text{cat}(c) \text{ searching}(e_b) \text{ actor}(e_c, b) \text{ object}(e_b, c)}$$
$$(K_b \sqcap K_c)^e = \frac{e}{\text{actor}(e, b)}$$

No common topic

(18) a. It rained in Riga.
 ??b. Then Arshak made dinner in Yerevan.] Narration

(19) a. My car broke down.] Narration
 ??b. Then the sun set.

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(19) a. My car broke down.] Narration
 ??b. Then the sun set.

(20) a. My car broke down.
 b. Then the sun set.] Narration
 c. I knew I was in trouble.] Result

Explanation and Result

- Explanation is **subordinating** and Result is **coordinating**.
 - > Homework: verify this for yourself with examples involving anaphora.
 - > If you find a cool one, show it to us!
- Both are veridical.

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e_π
<hr/>
$\text{cause}(e_\beta, e_\alpha)$
$\neg\text{before}(e_\alpha, e_\beta)$
$e_\pi = e_\beta + e_\alpha$

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<hr/>
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$e_\pi = e_\alpha + e_\beta$

Backgrounds and Backgrounds

(21) a. (π_1) John walked (π_2) while it was raining.

*Background*_{bckw} (π_1, π_2)

Backgrounds and Backgrounds

(21) a. (π_1) John walked (π_2) while it was raining.

*Background*_{bckw} (π_1, π_2)

b. (π_1) While it was raining, (π_2) John walked.

*Background*_{fwd} (π_1, π_2)

Backgrounds and Backgrounds

(21) a. (π_1) John walked (π_2) while it was raining.

*Background*_{bckw} (π_1, π_2)

b. (π_1) While it was raining, (π_2) John walked.

*Background*_{fwd} (π_1, π_2)

- These tell (arguably) the same story.
- So we need two backgrounds:
 - > The main story PRECEDES the background (*Background*_{backward})
 - > The main story FOLLOWS the background (*Background*_{foward})
- (Because we want the narrative structure to track the order of utterance; also see Asher, Prevot & Vieu (2007).)

- Both are veridical and subordinating.
 - > Is that right? The thing about subordination?
 - > Think about it. The cue-phrase is *while*.
- The following meaning postulate goes for both:

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- Easy enough, but...

Background has Magic Anaphora Properties!

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- a. While it was just drizzling,
 - b. a woman searched for shelter,
 - c. to not get wet.
- } Expl } Background_{fwd}

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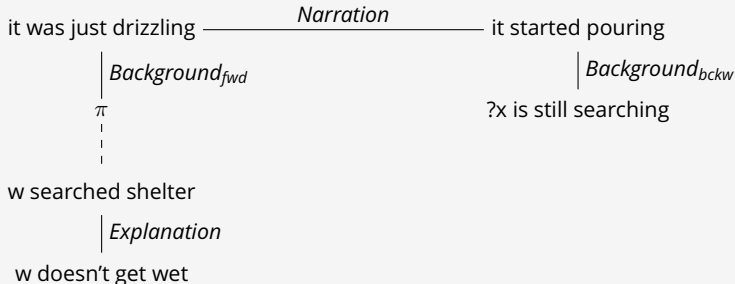
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- a. While it was just drizzling,
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 - d. then it started pouring
 - e. while **she** was still searching
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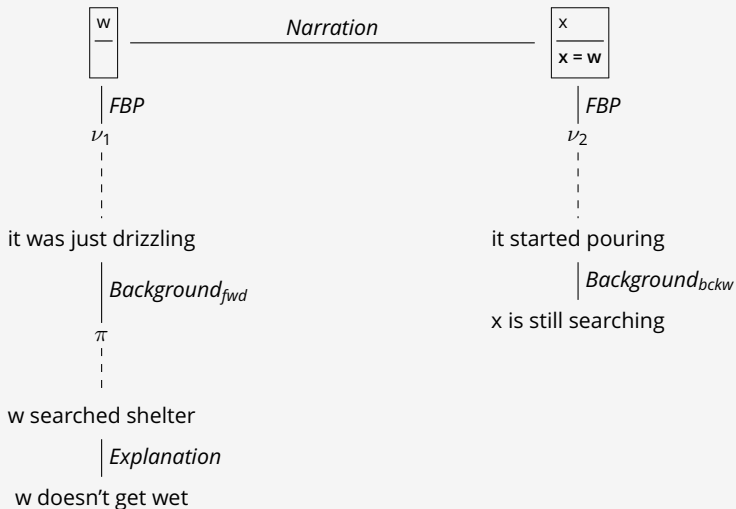
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- and add $\nu : \textit{Foreground-Background-Pair}(\lambda, \pi)$. (henceforth, *FBP*)



We will put a full glossary of the SDRT coherence relations
and their *Info's* online.

Evaluating SDRSs

- When we evaluate an entire SDRS $S = (\Pi, \mathcal{F}, L)$, we find its root label π_0 and compute $\llbracket \mathcal{F}(\pi_0) \rrbracket^S$.
 - > This is why the root label has to be unique: you need to know where to start.
- By design, this runs through the entire SDRS.
 - > This is why there cannot be any circles: this would never stop
- In some SDRSs we might hit the same label multiple times; this is harmless since this just repeats information we already know.

And if you want a classical truth-condition

- Let $S = (\Pi, \mathcal{F}, L)$ be an SDRS, w be a world, f, g be variable assignments and M be a model.
- So you start with a *set* of possible worlds W and an assignment f ,
 - > Typically (“null context”): W is all possible worlds, and f is empty
- And you compute which world-assignment pairs are not ruled out by the content of P :

$$\{(w, g) \mid f \llbracket P \rrbracket_{M, w}^S g\}$$

(23) π_1 : John had a great lunch.
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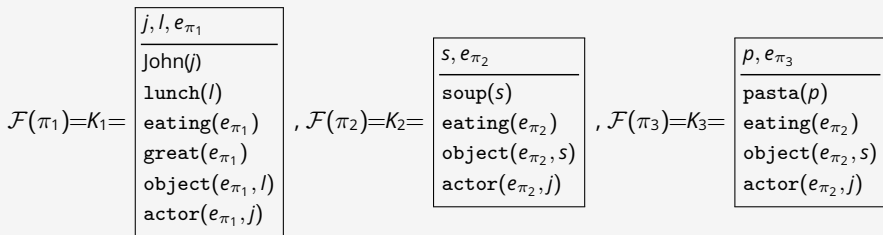
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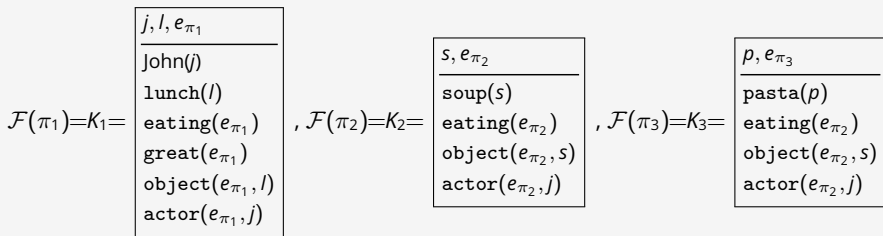
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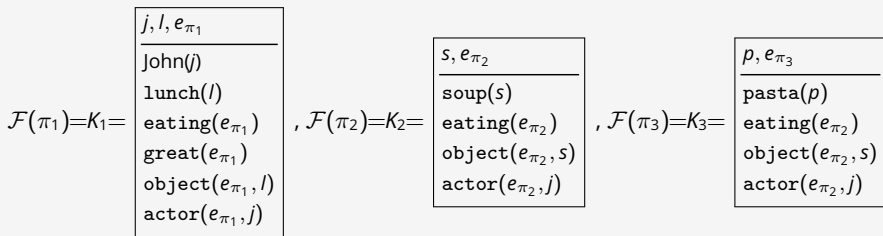


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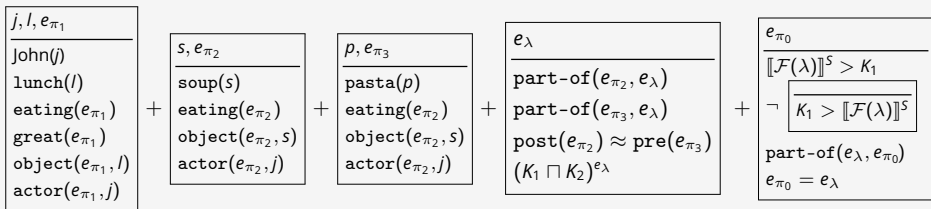
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$$= \llbracket K_1 \rrbracket^S + \llbracket K_2 \rrbracket^S + \llbracket K_3 \rrbracket^S + \left[\frac{e_\lambda}{\text{part-of}(e_{\pi_2}, e_\lambda)} \right. \\ \left. \text{part-of}(e_{\pi_3}, e_\lambda) \right. \\ \left. \text{post}(e_{\pi_2}) \approx \text{pre}(e_{\pi_3}) \right. \\ \left. (K_1 \sqcap K_2)^{e_\lambda} \right] + \llbracket \mathcal{F}(\lambda) > K_1 \wedge \neg(K_1 > \mathcal{F}(\lambda)) \wedge \left[\frac{e_{\pi_0}}{\text{part-of}(e_\lambda, e_{\pi_0})} \right]^S \left. \right] \\ e_{\pi_0} = e_\lambda$$

$$= + \llbracket K_1 \rrbracket^S + \left[\frac{e_\lambda}{\text{part-of}(e_{\pi_2}, e_\lambda)} \right. \\ \left. \text{part-of}(e_{\pi_3}, e_\lambda) \right. \\ \left. \text{post}(e_{\pi_2}) \approx \text{pre}(e_{\pi_3}) \right. \\ \left. (K_1 \sqcap K_2)^{e_\lambda} \right] + \left[\frac{\llbracket \mathcal{F}(\lambda) \rrbracket^S > K_1}{\llbracket \mathcal{F}(\lambda) \rrbracket^S > K_1} \right] + \left[\frac{\neg(K_1 > \llbracket \mathcal{F}(\lambda) \rrbracket^S)}{\neg(K_1 > \llbracket \mathcal{F}(\lambda) \rrbracket^S)} \right] + \left[\frac{e_{\pi_0}}{\text{part-of}(e_\lambda, e_{\pi_0})} \right]^S \\ e_{\pi_0} = e_\lambda$$

$$= \llbracket K_1 \rrbracket^S + \llbracket K_2 \rrbracket^S + \llbracket K_3 \rrbracket^S + \left[\frac{e_\lambda}{\text{part-of}(e_{\pi_2}, e_\lambda)} \right. \\ \left. \text{part-of}(e_{\pi_3}, e_\lambda) \right. \\ \left. \text{post}(e_{\pi_2}) \approx \text{pre}(e_{\pi_3}) \right. \\ \left. (K_1 \sqcap K_2)^{e_\lambda} \right] + \left[\frac{e_{\pi_0}}{\llbracket \mathcal{F}(\lambda) \rrbracket^S > K_1} \right. \\ \left. \neg(K_1 > \llbracket \mathcal{F}(\lambda) \rrbracket^S) \right. \\ \left. \text{part-of}(e_\lambda, e_{\pi_0}) \right. \\ \left. e_{\pi_0} = e_\lambda \right]$$



$$\begin{array}{|l} \hline j, l, e_{\pi_1} \\ \hline \text{John}(j) \\ \text{lunch}(l) \\ \text{eating}(e_{\pi_1}) \\ \text{great}(e_{\pi_1}) \\ \text{object}(e_{\pi_1}, l) \\ \text{actor}(e_{\pi_1}, j) \end{array} + \underbrace{\begin{array}{|l} \hline s, e_{\pi_2} \\ \hline \text{soup}(s) \\ \text{eating}(e_{\pi_2}) \\ \text{object}(e_{\pi_2}, s) \\ \text{actor}(e_{\pi_2}, j) \end{array} + \begin{array}{|l} \hline p, e_{\pi_3} \\ \hline \text{pasta}(p) \\ \text{eating}(e_{\pi_2}) \\ \text{object}(e_{\pi_2}, s) \\ \text{actor}(e_{\pi_2}, j) \end{array} + \begin{array}{|l} \hline e_{\lambda} \\ \hline \text{part-of}(e_{\pi_2}, e_{\lambda}) \\ \text{part-of}(e_{\pi_3}, e_{\lambda}) \\ \text{post}(e_{\pi_2}) \approx \text{pre}(e_{\pi_3}) \\ (K_1 \sqcap K_2)^{e_{\lambda}} \end{array}} = \mathcal{F}(\lambda) + \begin{array}{|l} \hline e_{\pi_0} \\ \hline \llbracket \mathcal{F}(\lambda) \rrbracket^S > K_1 \\ \boxed{\neg K_1 > \llbracket \mathcal{F}(\lambda) \rrbracket^S} \\ \text{part-of}(e_{\lambda}, e_{\pi_0}) \\ e_{\pi_0} = e_{\lambda} \end{array}$$

$$\begin{array}{|l} \hline j, l, e_{\pi_1} \\ \hline \text{John}(j) \\ \text{lunch}(l) \\ \text{eating}(e_{\pi_1}) \\ \text{great}(e_{\pi_1}) \\ \text{object}(e_{\pi_1}, l) \\ \text{actor}(e_{\pi_1}, j) \end{array} + \underbrace{\begin{array}{|l} \hline s, e_{\pi_2} \\ \hline \text{soup}(s) \\ \text{eating}(e_{\pi_2}) \\ \text{object}(e_{\pi_2}, s) \\ \text{actor}(e_{\pi_2}, j) \end{array} + \begin{array}{|l} \hline p, e_{\pi_3} \\ \hline \text{pasta}(p) \\ \text{eating}(e_{\pi_2}) \\ \text{object}(e_{\pi_2}, s) \\ \text{actor}(e_{\pi_2}, j) \end{array} + \begin{array}{|l} \hline e_{\lambda} \\ \hline \text{part-of}(e_{\pi_2}, e_{\lambda}) \\ \text{part-of}(e_{\pi_3}, e_{\lambda}) \\ \text{post}(e_{\pi_2}) \approx \text{pre}(e_{\pi_3}) \\ (K_1 \sqcap K_2)^{e_{\lambda}} \end{array}}_{= \mathcal{F}(\lambda)} + \begin{array}{|l} \hline e_{\pi_0} \\ \hline \llbracket \mathcal{F}(\lambda) \rrbracket^S > K_1 \\ \boxed{\neg K_1 > \llbracket \mathcal{F}(\lambda) \rrbracket^S} \\ \text{part-of}(e_{\lambda}, e_{\pi_0}) \\ e_{\pi_0} = e_{\lambda} \end{array}$$

$$(K_1 \sqcap K_2)^{e_{\lambda}} = \begin{array}{|l} \hline e_{\lambda} \\ \hline \text{eating}(e_{\lambda}) \\ \text{actor}(e_{\lambda}, j) \end{array}$$

j, l, e_{π_1}
John(j)
lunch(l)
eating(e_{π_1})
great(e_{π_1})
object(e_{π_1}, l)
actor(e_{π_1}, j)

+

$s, e_{\pi_2}, p, e_{\pi_3}, e_{\lambda}$
soup(s)
eating(e_{π_2})
object(e_{π_2}, s)
actor(e_{π_2}, j)
pasta(p)
eating(e_{π_2})
object(e_{π_2}, s)
actor(e_{π_2}, j)
part-of(e_{π_2}, e_{λ})
part-of(e_{π_3}, e_{λ})
post(e_{π_2}) \approx pre(e_{π_3})
eating(e_{λ})
actor(e_{λ}, j)

+

e_{π_0}	
$\llbracket \mathcal{F}(\lambda) \rrbracket^S > K_1$	
\neg <table border="1"> <tr> <td>$K_1 > \llbracket \mathcal{F}(\lambda) \rrbracket^S$</td> </tr> </table>	$K_1 > \llbracket \mathcal{F}(\lambda) \rrbracket^S$
$K_1 > \llbracket \mathcal{F}(\lambda) \rrbracket^S$	
part-of(e_{λ}, e_{π_0})	
$e_{\pi_0} = e_{\lambda}$	

$j, l, e_{\pi_1}, s, e_{\pi_2}, p, e_{\pi_3}, e_{\lambda}, e_{\pi_0}$

John(j)	soup(s)	object(e_{π_2}, s)
lunch(l)	eating(e_{π_2})	actor(e_{π_2}, j)
eating(e_{π_1})	object(e_{π_2}, s)	part-of(e_{π_2}, e_{λ})
great(e_{π_1})	actor(e_{π_2}, j)	part-of(e_{π_3}, e_{λ})
object(e_{π_1}, l)	pasta(p)	post(e_{π_2}) \approx pre(e_{π_3})
actor(e_{π_1}, j)	eating(e_{π_2})	part-of(e_{λ}, e_{π_0})
eating(e_{λ})	actor(e_{λ}, j)	$e_{\pi_0} = e_{\lambda}$

$s, e_{\pi_2}, p, e_{\pi_3}, e_{\lambda}$

soup(s)	object(e_{π_2}, s)
eating(e_{π_2})	actor(e_{π_2}, j)
object(e_{π_2}, s)	part-of(e_{π_2}, e_{λ})
actor(e_{π_2}, j)	part-of(e_{π_3}, e_{λ})
pasta(p)	post(e_{π_2}) \approx pre(e_{π_3})
eating(e_{π_2})	actor(e_{λ}, j)
eating(e_{λ})	

j, l, e_{π_1}

John(j)
lunch(l)
eating(e_{π_1})
great(e_{π_1})
object(e_{π_1}, l)
actor(e_{π_1}, j)

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j, l, e_{π_1}

John(j)
lunch(l)
eating(e_{π_1})
great(e_{π_1})
object(e_{π_1}, l)
actor(e_{π_1}, j)

>

$s, e_{\pi_2}, p, e_{\pi_3}, e_{\lambda}$

soup(s)	object(e_{π_2}, s)
eating(e_{π_2})	actor(e_{π_2}, j)
object(e_{π_2}, s)	part-of(e_{π_2}, e_{λ})
actor(e_{π_2}, j)	part-of(e_{π_3}, e_{λ})
pasta(p)	post(e_{π_2}) \approx pre(e_{π_3})
eating(e_{π_2})	actor(e_{λ}, j)
eating(e_{λ})	

⊃

$j, l, e_{\pi_1}, s, e_{\pi_2}, p, e_{\pi_3}, e_{\lambda}, e_{\pi_0}$

John(j)	soup(s)	object(e_{π_2}, s)
lunch(l)	eating(e_{π_2})	actor(e_{π_2}, j)
eating(e_{π_1})	object(e_{π_2}, s)	part-of(e_{π_2}, e_{λ})
great(e_{π_1})	actor(e_{π_2}, j)	part-of(e_{π_3}, e_{λ})
object(e_{π_1}, l)	pasta(p)	post(e_{π_2}) \approx pre(e_{π_3})
actor(e_{π_1}, j)	eating(e_{π_2})	part-of(e_{λ}, e_{π_0})
eating(e_{λ})	actor(e_{λ}, j)	$e_{\pi_0} = e_{\lambda}$

 $s, e_{\pi_2}, p, e_{\pi_3}, e_{\lambda}$

soup(s)	object(e_{π_2}, s)
eating(e_{π_2})	actor(e_{π_2}, j)
object(e_{π_2}, s)	part-of(e_{π_2}, e_{λ})
actor(e_{π_2}, j)	part-of(e_{π_3}, e_{λ})
pasta(p)	post(e_{π_2}) \approx pre(e_{π_3})
eating(e_{π_2})	actor(e_{λ}, j)
eating(e_{λ})	

 j, l, e_{π_1}

John(j)
lunch(l)
eating(e_{π_1})
great(e_{π_1})
object(e_{π_1}, l)
actor(e_{π_1}, j)

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(24)

 π_1 : John had a great lunch . π_2 : He ate soup. π_3 : Then he ate pasta. j, l, e_{π_1}

John(j)
lunch(l)
eating(e_{π_1})
great(e_{π_1})
object(e_{π_1}, l)
actor(e_{π_1}, j)

>

 $s, e_{\pi_2}, p, e_{\pi_3}, e_{\lambda}$

soup(s)	object(e_{π_2}, s)
eating(e_{π_2})	actor(e_{π_2}, j)
object(e_{π_2}, s)	part-of(e_{π_2}, e_{λ})
actor(e_{π_2}, j)	part-of(e_{π_3}, e_{λ})
pasta(p)	post(e_{π_2}) \approx pre(e_{π_3})
eating(e_{π_2})	actor(e_{λ}, j)
eating(e_{λ})	

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